PATENT COOPERATION TREATY

From the:
INTERNATIONAL PRELIMINARY EXITING AUTHORITY



PCT

Locata Corporation 401, Clunies Ross St Action, ACT Australia 2601 NOTIFICATION OF TRANSMITTAL OF INTERNATIONAL PRELIMINARY EXAMINATION REPORT

(PCT Rule 71.1)

Date of mailing day/month/year

- 6 AUG 2004

Applicant's or agent's file reference

Locata Co.

IMPORTANT NOTIFICATION

International Application No. **PCT/AU2003/001246**

International Filing Date 19 September 2003 Priority Date
20 September 2002

Applicant

LOCATA CORPORATION et al

- 1. The applicant is hereby notified that this International Preliminary Examining Authority transmits herewith the international preliminary examination report and its annexes, if any, established on the international application.
- 2. A copy of the report and its annexes, if any, is being transmitted to the International Bureau for communication to all the elected Offices.
- Where required by any of the elected Offices, the International Bureau will prepare an English translation of the report (but not of any annexes) and will transmit such translations to those Offices.

4. REMINDER

The applicant must enter the national phase before each elected Office by performing certain acts (filing translations and paying national fees) within 30 months from the priority date (or later in some Offices)(Article 39(1))(see also the reminder sent by the International Bureau with Form PCT/IB/301).

Where a translation of the international application must be furnished to an elected Office, that translation must contain a translation of any annexes to the international preliminary examination report. It is the applicant's responsibility to prepare and furnish such translation directly to each elected Office concerned.

For further details on the applicable time limits and requirements of the elected Offices, see Volume II of the PCT Applicant's Guide

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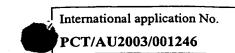
(PCT Article 36 and Rule 70)

Applicant's or agent's file reference Locata Co.	FOR FURTHER ACTION	See Notification of Transmittal of International Preliminary Examination Report (Form PCT/IPEA/416).				
International Application No.	International Filing Date (day/month/year)	Priority Date (day/month/year)				
PCT/AU2003/001246	19 September 2003	20 September 2002				
International Patent Classification (IPC) or national classification and IPC						
Int. Cl. 7 H01Q 3/24 H01Q 21/29						
Applicant						
LOCATA CORPORATION et a	LOCATA CORPORATION et al					
This international preliminary examination report has been prepared by this International Preliminary Examining Authority and is transmitted to the applicant according to Article 36.						
2. This REPORT consists of a total of 3						
This report is also accompanied by ANNEXES, i.e., sheets of the description, claims and/or drawings which have been amended and are the basis for this report and/or sheets containing rectifications made before this Authority (see Rule 70.16 and Section 607 of the Administrative Instructions under the PCT).						
These annexes consist of a total of	of 5 sheet(s).					
3. This report contains indications relating	g to the following items:					
I X Basis of the report						
II Priority	I Priority					
III Non-establishment of op	III Non-establishment of opinion with regard to novelty, inventive step and industrial applicability					
IV Lack of unity of invention	IV Lack of unity of invention					
V X Reasoned statement und citations and explanation	Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement					
VI Certain documents cited	Certain documents cited					
VII Certain defects in the int	Certain defects in the international application					
VIII Certain observations on	VIII Certain observations on the international application					
Date of submission of the demand		Date of completion of the report				
19 April 2004		3 August 2004				
Name and mailing address of the IPEA/AU		Authorized Officer				
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INTERNATIONAL PRELIMINARY EXAMINATION REPORT

I.		Basis of the repor				
1.	With	With regard to the elements of the international application:*				
		the international application as originally filed.				
	X	the description,	pages 1-15, as originally filed,			
			pages, filed with the demand,			
			pages, received on with the letter of			
	X	the claims,	pages , as originally filed,			
			pages , as amended (together with any statement) under Article 19,			
			pages, filed with the demand, pages 16-19, received on 23 July 2004 with the letter of 23 July 2004			
	[Tel	Ata a dana danan	pages 2-5, as originally filed,			
	X	the drawings,				
			pages, filed with the demand, pages 1, received on 23 July 2004 with the letter of 23 July 2004			
		the sequence list	ing part of the description:			
	Ш	are sequence not				
			pages, as originally filed pages, filed with the demand			
			pages, received on with the letter of			
2.	whic	With regard to the language, all the elements marked above were available or furnished to this Authority in the language in which the international application was filed, unless otherwise indicated under this item. These elements were available or furnished to this Authority in the following language which is: the language of a translation furnished for the purposes of international search (under Rule 23.1(b)).				
		the language of publication of the international application (under Rule 48.3(b)).				
	ᆜ	_				
		and/or 55.3).	the translation furnished for the purposes of international preliminary examination (under Rules 55.2			
3.	With	With regard to any nucleotide and/or amino acid sequence disclosed in the international application, the international preliminary examination was carried out on the basis of the sequence listing:				
			international application in written form.			
		filed together with the international application in computer readable form.				
		furnished subsec	quently to this Authority in written form.			
		furnished subsequently to this Authority in computer readable form.				
	The statement that the subsequently furnished written sequence listing does not go beyond the disclosure international application as filed has been furnished.		plication as filed has been furnished.			
		The statement the been furnished	nat the information recorded in computer readable form is identical to the written sequence listing has			
4.		The amendment	ts have resulted in the cancellation of:			
		the des	cription, pages			
		the clai	ims, Nos.			
		the dra	·			
5.		go beyond the d	been established as if (some of) the amendments had not been made, since they have been considered to lisclosure as filed, as indicated in the Supplemental Box (Rule 70.2(c)).**			
*	Replacement sheets which have been furnished to the receiving Office in response to an invitation under Article 14 are referred to in this report as "originally filed" and are not annexed to this report since they do not contain amendments (Rules 70.16 and 70.17).					
	Any replacement sheet containing such amendments must be referred to under item 1 and annexed to this report					

INTERNATIONAL PRELIMINARY EXAMINATION REPORT



v.	Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations
	and explanations supporting such statement

and explanations supporting such statement				
1. Statement				
Claims 1-20	YES			
Claims	NO			
Claims 1-20	YES			
Claims	NO			
Claims 1-20	YES			
Claims	NO			
	Claims 1-20 Claims Claims 1-20 Claims Claims Claims			

2. Citations and explanations (Rule 70.7)

It is apparent that none of the citations in the search report, individually or in combination, disclose the features of the claims 1-20 as indicated above. Furthermore, none of the distinguishing features over prior art would either be obvious to a person skilled in the art or would merely amount to adding common general knowledge. The claims are, therefore, novel and inventive.





- 1. A method for determining accurate range measurements in multipath and poor signal-to-noise ratio environments and subsequently improving location determination at a position receiver incorporating a directionally agile beam antenna, said position receiver configured to receive Time Division Multiple Access (TDMA) positioning signals transmitted by a network of synchronized positioning-unit devices at known locations, the method comprising:
 - a) calculating the location of said position receiver from said received Time Division Multiple Access
 (TDMA) positioning signals, and
 - b) steering said directionally agile beam antenna directional gain pattern exclusively towards the origin of the currently received Time Division Multiple Access (TDMA) positioning signal, said steering responsive to:
 - i) said calculated location of said position receiver, and
 - ii) said known locations of said synchronized positioning-unit devices.

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- 2. The method of claim 1, wherein said calculating the location of said position receiver from said received Time Division Multiple Access (TDMA) positioning signals additionally includes a calculation of a network time of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering is additionally responsive to said calculated network time.
- 3. The method of claim 1, wherein said calculating the location of said position receiver from said received Time Division Multiple Access (TDMA) positioning signals additionally includes the determination of a Time Division Multiple Access (TDMA) sequence of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering is additionally responsive to said determined Time Division Multiple Access (TDMA) sequence.
- 4. The method of claim 1, wherein said calculating the location of said position receiver from said received Time Division Multiple Access (TDMA) positioning signals additionally includes a calculation of the propagation delay of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering is additionally responsive to said calculated propagation delay.

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5. The method of claim 1 wherein said position receiver incorporating a directionally agile beam antenna is further configured with an attitude determination means, said calculating includes an additional step of determining the attitude of said position receiver, and said steering is additionally responsive to said determined attitude.

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- 6. A method for determining accurate range measurements in multipath and poor signal-to-noise ratio environments in a Time Division Multiple Access (TDMA) location network and subsequently improving the location determination at a position receiver, the method comprising:
 - a) deploying a plurality of synchronized positioning-unit devices at known locations transmitting positioning signals in a Time Division Multiple Access (TDMA) sequence;
 - deploying said position receiver configured with a directionally agile beam antenna;
 - c) configuring said directionally agile beam antenna to receive said positioning signals from substantially all directions;
 - d) calculating the location of said position receiver from said received positioning signals;
- e) reconfiguring said directionally agile beam antenna to receive said positioning signals from substantially one direction;
 - f) steering said reconfigured said directionally agile beam antenna directional gain pattern exclusively towards the origin of the currently received positioning signal, said steering responsive to:
 - i) said calculated location of said position receiver, and

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- ii) said known locations of said synchronized positioning-unit devices.
- 7. The method of claim 6, wherein said calculating the location of said position receiver from said received positioning signals additionally includes a calculation of a network time of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering is additionally responsive to said calculated network time.
- 8. The method of claim 6, wherein said calculating the location of said position receiver from said received positioning signals additionally includes a determination of a Time Division Multiple Access (TDMA) sequence of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering is additionally responsive to said determined Time Division Multiple Access (TDMA) sequence.
- 9. The method of claim 6, wherein said calculating the location of said position receiver from said received positioning signals additionally includes a calculation of the propagation delay of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering is additionally

responsive to said calculated propagation delay.

10. The method of claim 6, wherein said position receiver configured with a directionally agile beam antenna is further configured with an attitude determination means, said calculating includes an additional step of determining the attitude of said position receiver, and said steering is additionally responsive to said determined attitude.



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- 11. A system for determining accurate range measurements in multipath and poor signal-to-noise ratio environments in a Time Division Multiple Access (TDMA) location network, the system comprising:
 - a) a plurality of synchronized positioning-unit devices at known locations transmitting positioning signals in a Time Division Multiple Access (TDMA) sequence;
 - b) a position receiver configured with a directionally agile beam antenna;
 - c) means configured to calculate the location of said position receiver from said transmitted positioning signals;
 - d) means configured to steer said directionally agile beam antenna directional gain pattern exclusively towards the origin of the currently received positioning signal, said steering responsive to:
 - i) said calculated location of said position receiver, and
 - ii) said known locations of said synchronized positioning-unit devices.
- 12. The system of claim 11, wherein said means configured to calculate the location of said position receiver additionally includes a means configured to calculate a network time of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering means is additionally responsive to said calculated network time.
- 13. The system of claim 11, wherein said means configured to calculate the location of said position receiver additionally includes a means configured to determine a Time Division Multiple Access (TDMA) sequence of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering means is additionally responsive to said determined Time Division Multiple Access (TDMA) sequence.
 - 14. The system of claim 11, wherein said means configured to calculate the location of said position receiver additionally includes a means configured to calculate the propagation delay of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering means is additionally responsive to said calculated propagation delay.
 - 15. The system of claim 11, wherein said position receiver configured with a directionally agile beam antenna is further configured with an attitude determination means, said means configured to calculate the location of said position receiver includes an additional means configured to determine the attitude of said position receiver, and said steering means is additionally responsive to said determined attitude.



- 16. A system for determining accurate range measurements in multipath and poor signal-to-noise ratio environments in a Time Division Multiple Access (TDMA) location network, the system comprising:
 - a) a plurality of synchronized positioning-unit devices at known locations transmitting positioning signals in a Time Division Multiple Access (TDMA) sequence;
 - b) a position receiver configured with a directionally agile beam antenna;

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- c) means configured to adjust said directionally agile beam antenna to receive said transmitted positioning signals from substantially all directions;
- d) means configured to calculate the location of said position receiver from said transmitted positioning signals;
- e) means configured to readjust said directionally agile beam antenna to receive said transmitted positioning signals from substantially one direction;
- f) means configured to steer said directionally agile beam antenna directional gain pattern exclusively towards the origin of the currently received positioning signal, said steering responsive to:
 - i) said calculated location of said position receiver, and
- ii) said known locations of said synchronized positioning-unit devices.
- 17. The system of claim 16, wherein said means configured to calculate the location of said position receiver additionally includes a means configured to calculate a network time of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering means is additionally responsive to said calculated network time.
- 18. The system of claim 16, wherein said means configured to calculate the location of said position receiver additionally includes a means configured to determine a Time Division Multiple Access (TDMA) sequence of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering means is additionally responsive to said determined Time Division Multiple Access (TDMA) sequence.
- 19. The system of claim 16, wherein said means configured to calculate the location of said position receiver additionally includes a means configured to calculate the propagation delay of said positioning signals transmitted by said positioning-unit devices at known locations, and said steering means is additionally responsive to said calculated propagation delay.
- 20. The system of claim 16, wherein said position receiver configured with a directionally agile beam antenna is further configured with an attitude determination means, said means configured to calculate the location of said position receiver includes an additional means configured to determine the attitude of said position receiver, and said steering means is additionally responsive to said determined attitude.